

# EPM50 SERIES

## Diameter $\phi$ 50mm Shaft type Absolute Multi-turn Rotary encoders

NEW

### Features

- Compact size of diameter  $\phi$  50mm
- Parallel data / SSI data transmission type
- **Total 23bit resolution(8388608 divisions) of 10bit single-turn(1024 divisions) and 13bit multi-turn (8192 divisions)**
- Easy zero adjustment using single-turn / multi-turn data separated reset function
- Memorizing revolution data up to  $\pm 90^\circ$  after blackout without memory back up function
- Possible CW/CCW direction setting with direction function
- Maximizing users convenience with lclear, overflow alarm (OVF) function
- Protection structure IP64 (Partial waterproof, Oil proof)
- Provides Latch fuction (Parallel output model only)



### Applications

Precision machine tool, Fabric machinery, Robot, Parking system

**!** Please read "Caution for your safety" in operation manual before using.



### Ordering information

<b>EPM50S</b>	<b>8</b>	-	<b>10</b>	<b>13</b>	-	<b>B</b>	-	<b>PN</b>	-	<b>24</b>
Series	Shaft diameter	Single-turn	Multi-turn	Output code	Control output				Power supply	
Diameter $\phi$ 50mm	$\phi$ 8mm	10bit (1024 division)	13bit (8192 division)	Binary Code	PN: Parallel NPN open collector output S : SSI				12-24VDC $\pm$ 5%	

### Specifications

Type		$\phi$ 50mm Multi-turn absolute encoder		
Model		<b>EPM50S8-1013-B-S-24</b>	<b>EPM50S8-1013-B-PN-24</b>	
Resolution	Single-turn	1024 division (10Bit)		
	Multi-turn	8192 revolution (13Bit)		
Rotation limit when power is off		<b>(★1)</b> $\pm 90^\circ$		
Electrical specification	Output	Output code	24bit, Binary 2 code	Binary 2 code
		Output Interface	SSI (Synchronous Serial Interface)	Parallel
		Output type	Line driver	NPN open collector output
		Output signal	Single-turn data, Multi-turn count, <b>(★2)</b> OVF alarm	
		Line driver output	<ul style="list-style-type: none"> <li>• Low: Sink current - max. 20mA, Residual voltage - max. 0.5VDC</li> <li>• High: Sink current - max. -20mA, Output voltage - max. 2.5VDC</li> </ul>	—
		NPN open collector output	—	Sink current : Max. 32mA, Residual voltage : Max. 1VDC
		Logic	—	Negative logic output
		Response time	—	Max. 1 $\mu$ s (Cable: 2m, I sink = 32mA)
Input	Input signal	<b>(★3)</b> Single-turn data reset, <b>(★4)</b> Multi-turn count reset, Direction, Clear		
		—	Latch	
	Input level	High : 5-24VDC, Low : 0-1.2VDC		
	Input logic	<b>(★5)</b> Low active, HIGH or OPEN for common use		
	Input time	Direction : Over 100ms		
		Single-turn data reset : Over 100ms	Multi-turn count reset : Over 100ms	
Clear : Over 100ms				
SSI Clock Input Frequency	100kHz to 1MHz	—	Latch : Over 500 $\mu$ s	

※ **(★1)** It calibrates the multi-turn counts by comparing single-turn data before/after power off without counting multi-turn counts when power is off. It shall be used on the condition that no over-rated revolution occurred since proper multi-turn data may not be available if any revolutions occurred over  $\pm 90^\circ$  from the position when power is off.

※ **(★2)** OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolution).

It shall be initialized by changing the setting of direction or applying multi-turn count reset or clear signals.

※ **(★3)** Single-turn data shall be initialized as 「0」 when single-turn data reset is input.

※ **(★4)** Multi-turn count shall be initialized as 「0 revolution」 when multi-turn count reset is input.

※ **(★5)** High active is customizable.

# ∅ 50mm Shaft Multi-turn Absolute Type

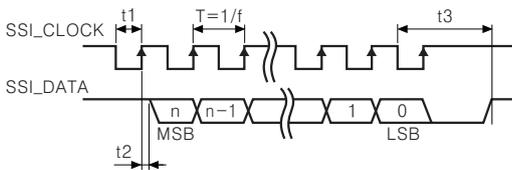
## Specifications

Type	∅ 50mm Multi-turn absolute encoder		
Model	<b>EPM50S8-1013-B-S-24</b>	<b>EPM50S8-1013-B-PN-24</b>	
Electrical specification	Max. Response frequency	50kHz	
	Power supply	12-24VDC, ±5% (Ripple P-P : Max. 5%)	
	Current consumption	Max. 150mA (Disconnection of the load)	Max. 100mA (Disconnection of the load)
	Insulation resistance	Min. 100MΩ (At 500VDC between all terminals and case)	
	Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)	
Connection	Cable outgoing type (Cable gland)		
Mechanical specification	Starting torque	Max. 40gf · cm (0.004N · m)	
	Moment of inertia	Max. 40g · cm <sup>2</sup> (4 × 10 <sup>-6</sup> kg · m <sup>2</sup> )	
	Shaft loading	Radial : 10kgf, Thrust : 2.5kgf	
	Max. revolution	<b>(★6)</b> 3000rpm	
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for one minute cycle) in each of X, Y, Z direction for 2 hours		
Shock	Max. 50G		
Ambient temperature	-10 to 70°C (At non-freezing status), Storage : -25 to 85°C		
Ambient humidity	35 to 85%RH		
Protection	IP64 (IEC standard)		
Cable	∅ 6mm 10P, Length : 2m, Shield cable	∅ 6mm 17P × 2, Length : 2m, Shield cable	
Accessory	Mounting bracket, Coupling		
Approval	<b>CE</b>		
Unit weight	Approx. 322g	Approx. 475g	

※ (★6) In case of Parallel type model, select the resolution to make max. response revolution is lower than max. allowable revolution.

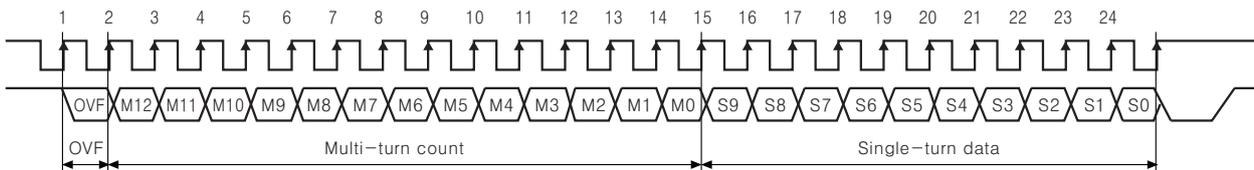
$$\text{【Max. Response Revolution (rpm) = } \frac{\text{Max. Allowable Revolution}}{\text{Resolution}} \times 60 \text{ sec.】}$$

## Synchronous serial interface (SSI) Output Timing diagram



Clock Frequency f	100kHz to 1MHz
T	T : 1 to 10μs
	0.5μs < t1 < 5μs
Time lag t2	t2 < 0.3μs
Monoflop Time t3	15μs < t3 < 30μs

## Synchronous serial interface (SSI) Data Output

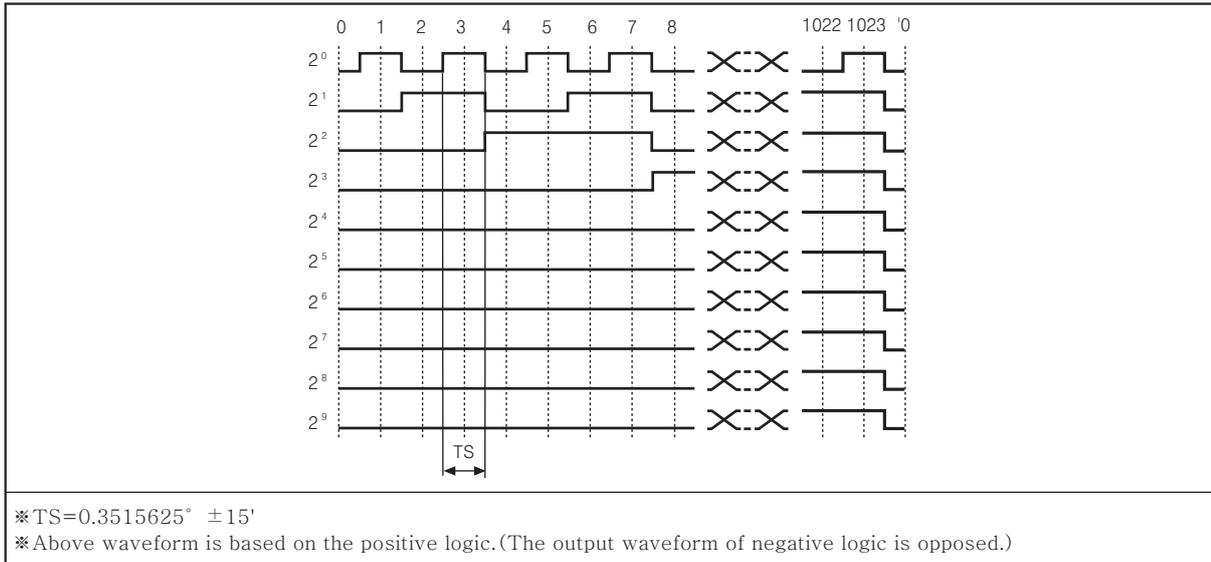


Clock input bit	Data output name	Data output bit	Clock input bit	Data output name	Data output bit
1	Over flow error bit	0 bit	15	Single-turn data	9 bit (MSB)
2	Multi-turn count	12 bit (MSB)	16		8 bit
3		11 bit	17		7 bit
4		10 bit	18		6 bit
5		9 bit	19		5 bit
6		8 bit	20		4 bit
7		7 bit	21		3 bit
8		6 bit	22		2 bit
9		5 bit	23		1 bit
10		4 bit	24		0 bit (LSB)
11		3 bit			
12		2 bit			
13		1 bit			
14	0 bit (LSB)				

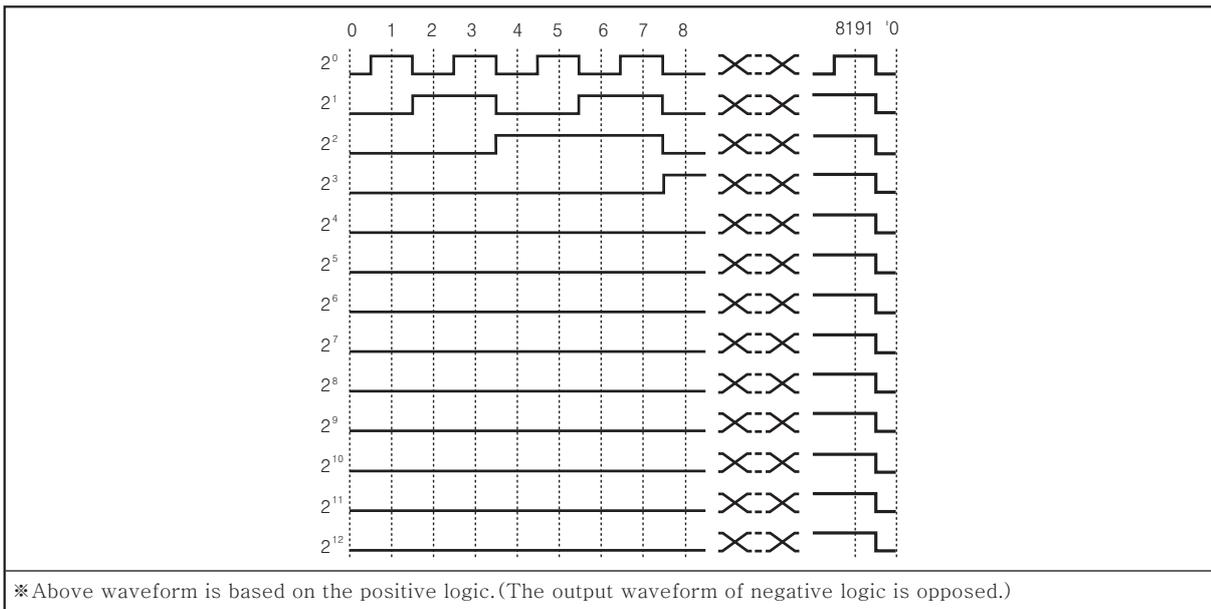
- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
- (D) Proximity sensor
- (E) Pressure sensor
- (F) Rotary encoder
- (G) Connector/Socket
- (H) Temp. controller
- (I) SSR/Power controller
- (J) Counter
- (K) Timer
- (L) Panel meter
- (M) Tacho/Speed/Pulse meter
- (N) Display unit
- (O) Sensor controller
- (P) Switching power supply
- (Q) Stepping motor & Driver & Controller
- (R) Graphic/Logic panel
- (S) Field network device
- (T) Production stoppage models & replacement

# EPM50 SERIES

## Parallel Interface 1024 division single-turn data output waveform (Binary code)

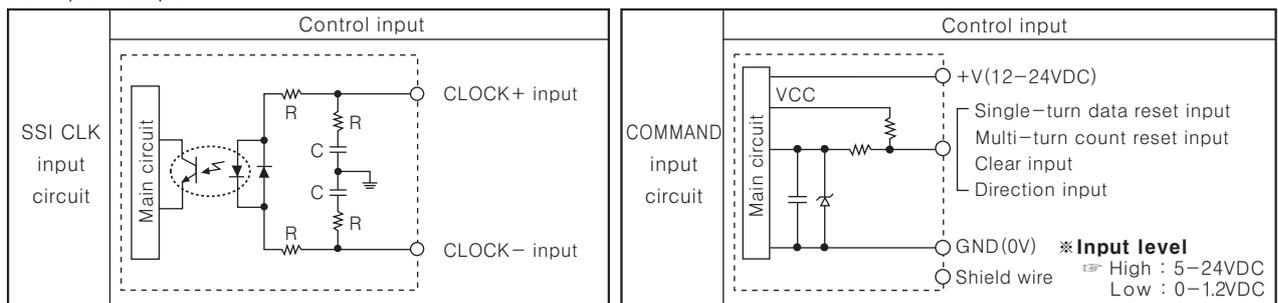


## Parallel Interface 8192 revolution multi-turn count data output waveform (Binary code)



## Control output I/O circuit

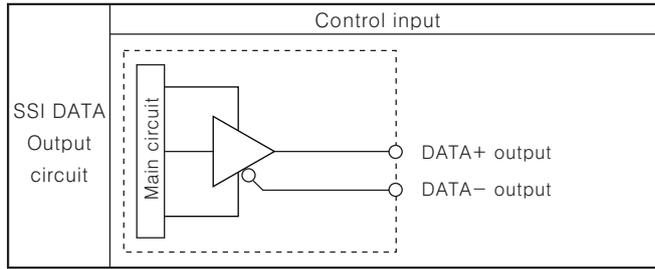
- SSI input • output



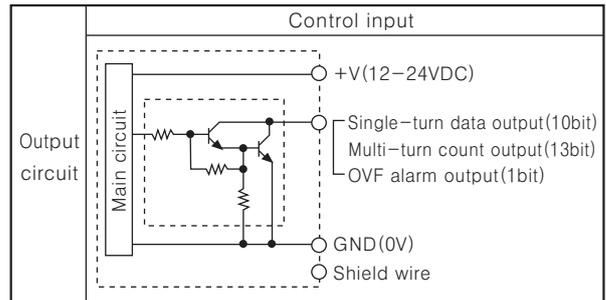
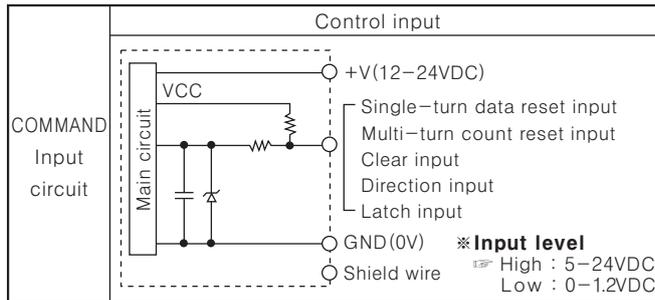
# ∅ 50mm Shaft Multi-turn Absolute Type

## Control output I/O circuit

### SSl output



### Parallel input • output



- \* Output of each bit is the same circuit.
- \* Overload or short may cause circuit break.

## Connections

### SSl output

Cable			
Cable color	Description	Cable color	Description
Brown	CLOCK +	Gray	Single-turn data reset
Red	CLOCK -	Blue	Multi-turn count reset
Orange	DATA +	Purple	Clear
Yellow	DATA -	Green	Direction
White	+V (12-24VDC)		
Black	GND (0V)		
Shield wire	Signal shield cable(F.G)		

### Parallel output

Multi-turn count cable(Sheath color : Black)			Single-turn data cable(Sheath color : Gray)		
Cable color	Description		Cable color	Description	
Brown	Multi-turn count	2 <sup>0</sup>	Brown	Single-turn data	2 <sup>0</sup>
Red		2 <sup>1</sup>	Red		2 <sup>1</sup>
Orange		2 <sup>2</sup>	Orange		2 <sup>2</sup>
Yellow		2 <sup>3</sup>	Yellow		2 <sup>3</sup>
Green		2 <sup>4</sup>	Green		2 <sup>4</sup>
Blue		2 <sup>5</sup>	Blue		2 <sup>5</sup>
Purple		2 <sup>6</sup>	Purple		2 <sup>6</sup>
Gray		2 <sup>7</sup>	Gray		2 <sup>7</sup>
Pink		2 <sup>8</sup>	Pink		2 <sup>8</sup>
Clear		2 <sup>9</sup>	Clear		2 <sup>9</sup>
Light brown		2 <sup>10</sup>	Light brown	NC	
Light yellow		2 <sup>11</sup>	Light yellow	Direction	
Light green	2 <sup>12</sup>	Light green	Latch		
Light blue	OVF		Light blue	Clear	
Light purple	Multi-turn count reset		Light purple	Single-turn data reset	
White	+V(12-24VDC)		White	+V(12-24VDC)	
Black	GND(0V)		Black	GND(0V)	
Shield wire	Signal shield cable(F.G)		Shield wire	Signal shield cable(F.G)	

- \* Please wire properly.
- \* As for parallel output, it is recommended to connect +V and GND of both multi-turn count cable and single-turn data cable.
- \* The metal case and shield wire of encoder should be grounded (F.G).
- \* Input/Output cable must not be short-circuited, because Driver IC is used in output circuit.

- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
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- (E) Pressure sensor
- (F) Rotary encoder
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